

Regression linéaire

$$y(x) = \beta_0 + \beta_1 x_1 + \dots + \beta_D x_D$$

→ Corrélation entre caractéristiques $\Rightarrow \beta_j \gg$

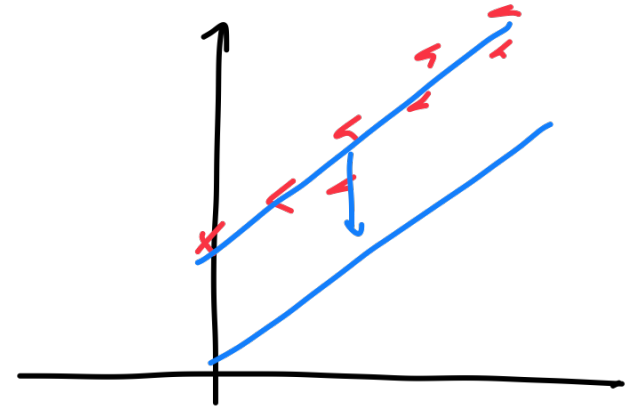
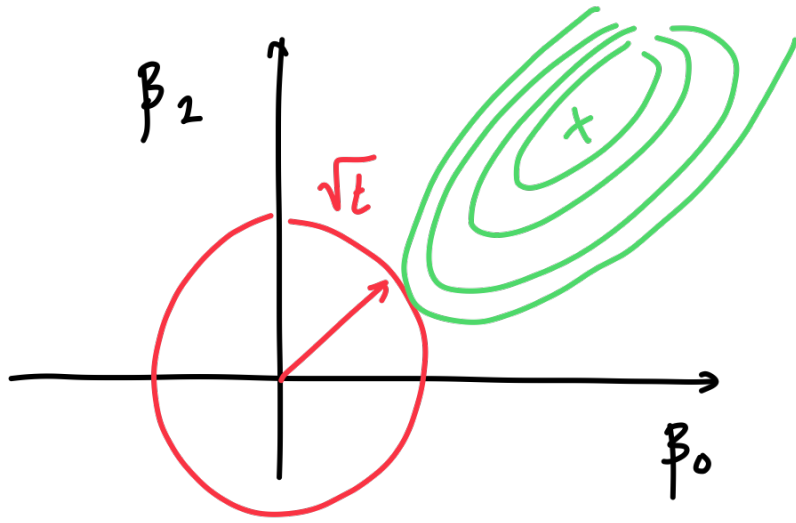
↳ Solution #1 : Sélection de caractéristiques

Solution #2 : Contrôle de l'amplitude de β_j

$$l(\beta) = \underbrace{\frac{1}{N} \sum_{i=1}^N (t^{(i)} - (\beta_0 + \beta_1 x_1^{(i)} + \dots + \beta_D x_D^{(i)}))^2}_{\text{Fidélité aux données}} + \underbrace{\lambda \sum_{j=1}^D |\beta_j|^2}_{\text{Penalité sur la complexité}} \quad \leftarrow$$

Penalité RIDGE

Penalité sur
la complexité



Pour trouver le minimum de la formulation Ridge
on commence par centrer les données

$$t^{(i)} \leftarrow t^{(i)} - \frac{1}{N} \sum_{i=1}^N t^{(i)}$$

$$x_j^{(i)} \leftarrow x_j^{(i)} - \frac{1}{N} \sum_{i=1}^N x_j^{(i)}$$

$$\rightarrow \beta_0 = 0$$

$$\mathcal{L}(\beta) = \frac{1}{N} \sum_{i=1}^N (t^{(i)} - (\beta_1 x_1^{(i)} + \dots + \beta_D x_D^{(i)}))^2 + \lambda \sum_{j=1}^D |\beta_j|^2$$

→ Soit $\vec{\beta} = (\beta_1, \beta_2, \dots, \beta_D)$ $\vec{t} = [t^{(2)} \dots t^{(N)}]^T$

$$\underline{\underline{X}} = \begin{bmatrix} x_1^{(2)} & \dots & x_D^{(2)} \\ \vdots & & \vdots \\ x_1^{(N)} & \dots & x_D^{(N)} \end{bmatrix}$$

$$\vec{\epsilon} = \vec{t} - \underline{\underline{X}} \vec{\beta}$$

vecteur des résidus

$$\mathcal{L}(\beta) = \frac{1}{N} \epsilon^T \epsilon + \lambda \beta^T \beta = \frac{1}{N} (\vec{t} - \underline{\underline{X}} \vec{\beta})^T (\vec{t} - \underline{\underline{X}} \vec{\beta}) + \lambda \vec{\beta}^T \vec{\beta}$$

$$\ell(\beta) = \frac{1}{N} [\vec{E}^T \vec{E} - \beta^T \underline{\underline{X}}^T \vec{E} - \vec{E}^T \underline{\underline{X}} \beta + \vec{\beta}^T \underline{\underline{X}}^T \underline{\underline{X}} \beta + \lambda \vec{\beta}^T \vec{\beta}]$$

$$\frac{\partial \ell}{\partial \beta} = \begin{matrix} \downarrow \\ 0 \end{matrix} - \cancel{\underline{\underline{X}}^T \vec{E}} + \cancel{\underline{\underline{X}}^T \underline{\underline{X}} \vec{\beta}} + \cancel{\lambda \vec{\beta}} = 0$$

$$(\underline{\underline{X}}^T \underline{\underline{X}} + \lambda \mathbf{I}) \vec{\beta} = \underline{\underline{X}}^T \vec{E}$$

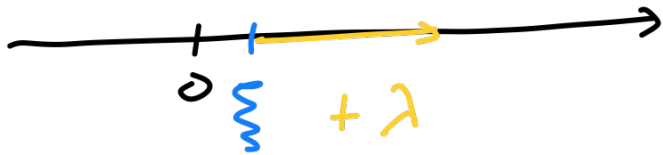
→ caractéristiques cornéées / colonnes linéairement dépendantes

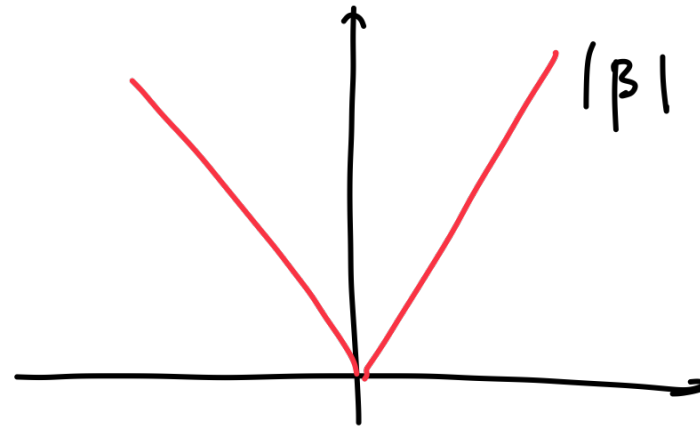
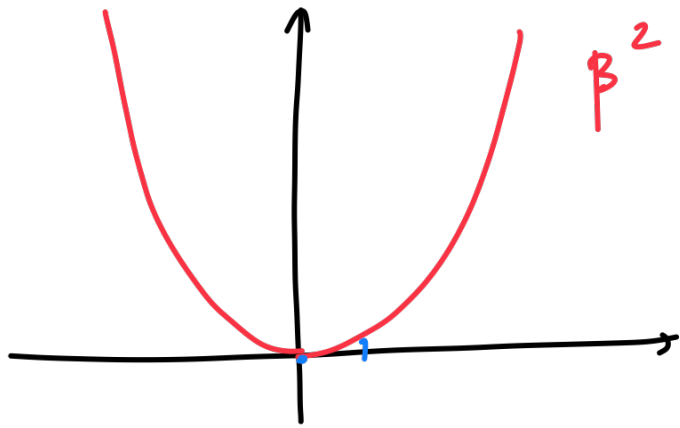
$$\exists v. t. q. \quad \underline{\underline{X}}^T \underline{\underline{X}} v = 0 \quad (\exists \lambda = 0 \text{ t. q. } \underline{\underline{X}}^T \underline{\underline{X}} v = \lambda v)$$

Soit (x, ξ) vecteur propre / valeur propre de $\underline{\underline{X}}^T \underline{\underline{X}}$

$\forall (\underline{v}, \lambda)$ on a $\left(\underline{X}^T \underline{X} + \lambda \underline{I} \right) \underline{v} = \underline{\xi} \underline{v} + \lambda \underline{v} = (\underline{\xi} + \lambda) \underline{v}$

Quand on ajoute $\lambda \underline{I}$ à $\underline{X}^T \underline{X}$ on translate les valeurs propres de $\underline{X}^T \underline{X}$ de λ





→ Regularisation LASSO

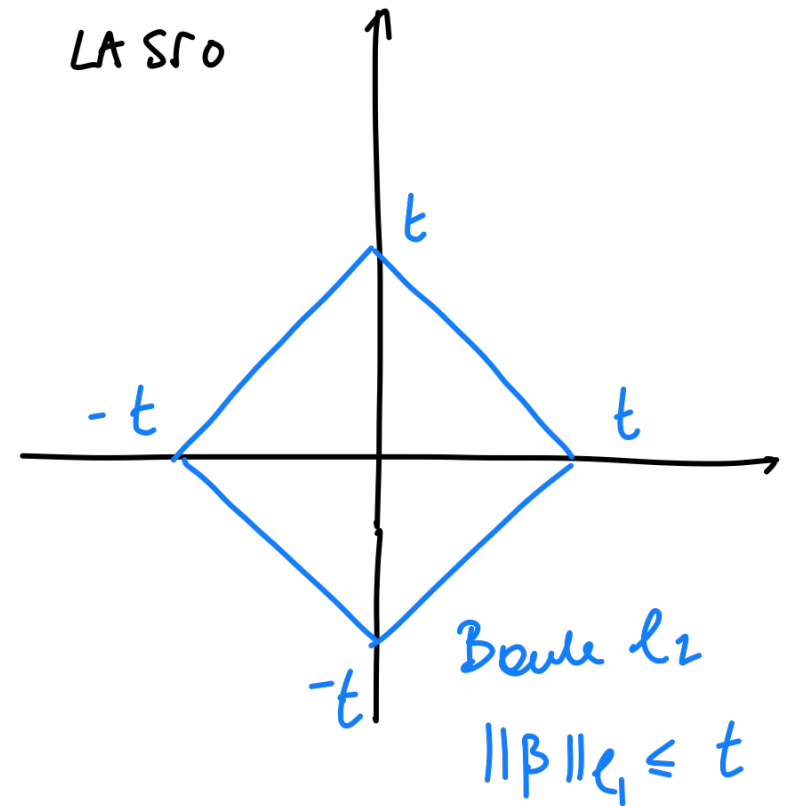
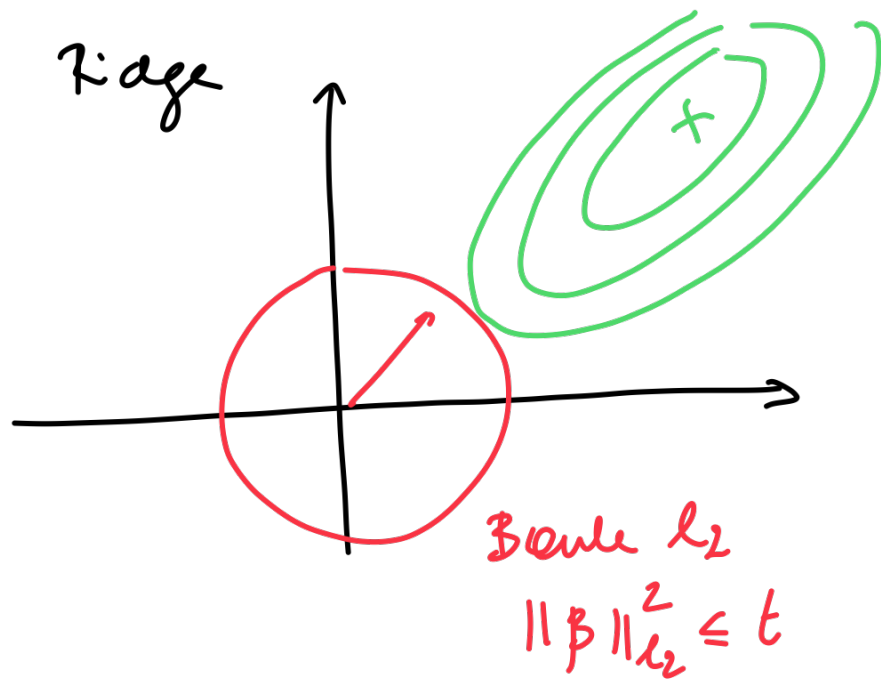
$$\mathcal{L}(\beta) = \frac{1}{N} \sum_{i=1}^N (t^{(i)} - (\beta_0 + \beta_1 x_1^{(i)} + \dots + \beta_D x_D^{(i)}))^2 + \lambda \sum_{j=1}^D |\beta_j|$$

Les pénalités Ridge et LASSO sont des cas particuliers de normes ℓ_p

$$\|\vec{\beta}\|_p = \left(\sum_{j=1}^D |\beta_j|^p \right)^{1/p}$$

Ridge $\Rightarrow$ norme ℓ_2 $\|\vec{\beta}\|_2^2$

LASSO $\Rightarrow$ norme ℓ_1 $\|\vec{\beta}\|_1$



Formulation Constraint

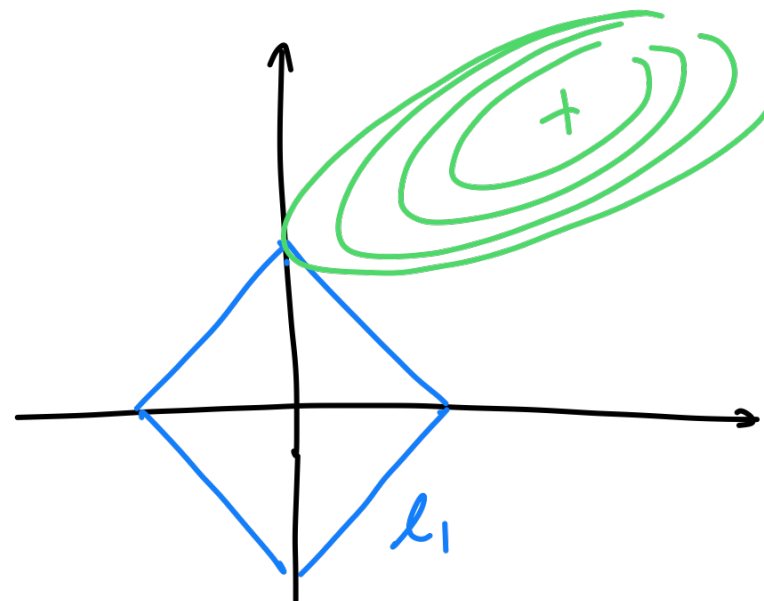
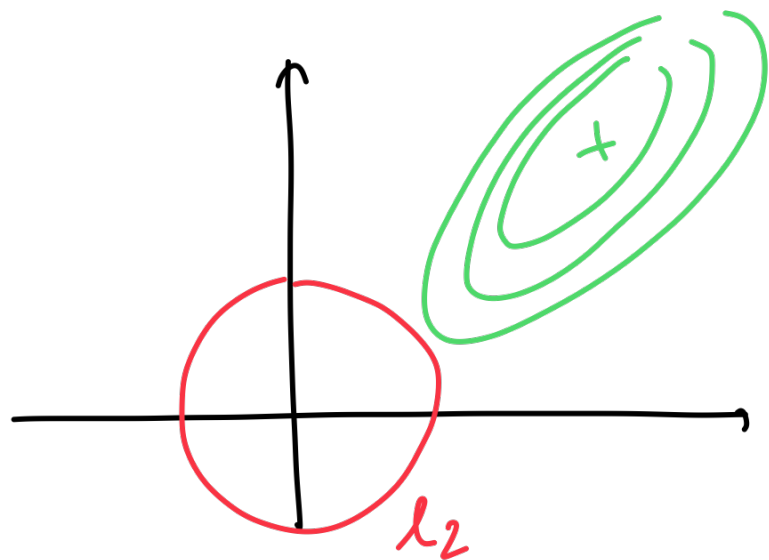
with $\frac{1}{N} \sum_{i=1}^N (t^{(i)} - (\beta_0 + \beta_1 x_1^{(i)} + \dots + \beta_D x_D^{(i)}))^2$

s.t

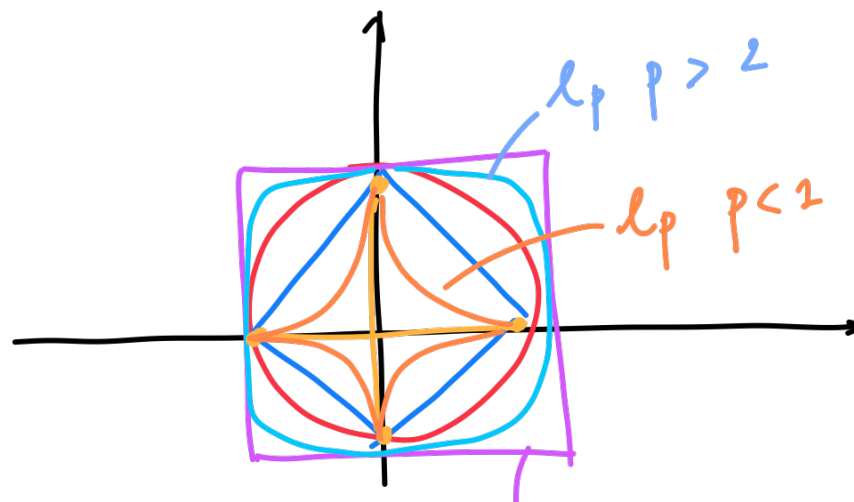
$$\sum_{j=1}^D |\beta_j| \leq t$$

"Banale l_1 "

$$\|\vec{\beta}\|_{l_1} \leq t$$



Previous $t=1$



l_p
 $p \rightarrow \infty$

$$\|\beta\|_{l_p} = \left(\sum |\beta_j|^p \right)^{1/p}$$

$$\|\beta\|_{\infty} \leq t$$

$\Leftrightarrow$

$$\max_j |\beta_j| \leq t$$

$$\|\beta\|_{\infty} = \max_j |\beta_j|$$

